

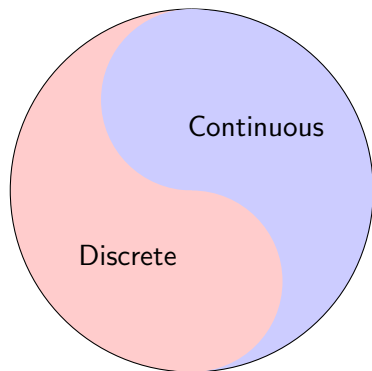
# Learning and Inference in Hybrid Models

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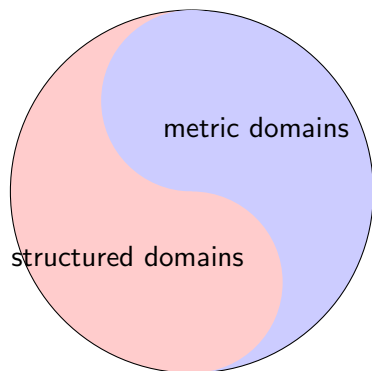
XAI seminars  
Imperial College London UK

# Hybrid Model



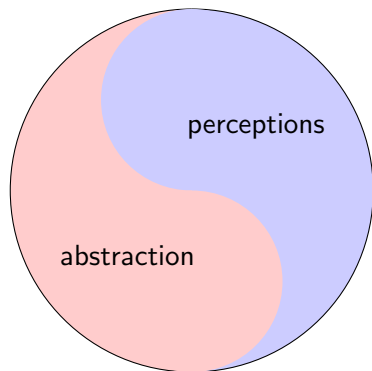
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- learning with hybrid models;
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# Hybrid Model



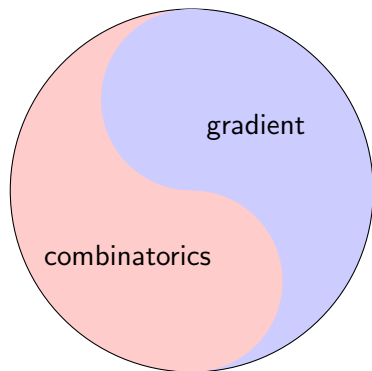
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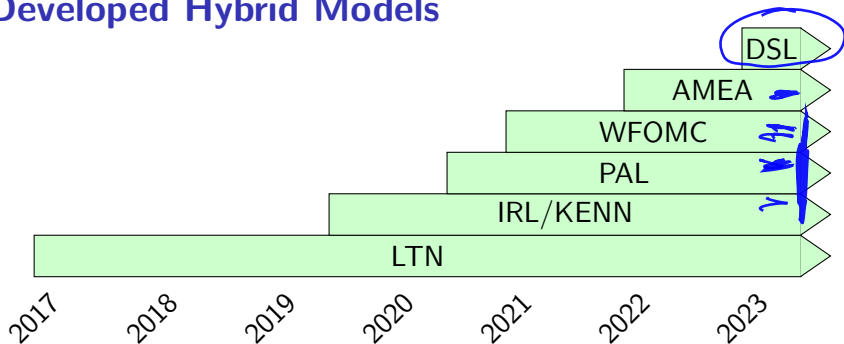
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# Developed Hybrid Models



**LTN** Logic Tensor Networks

**IRL/KENN** Incremental Refinement Layer/Knowledge Enhanced Neural Network

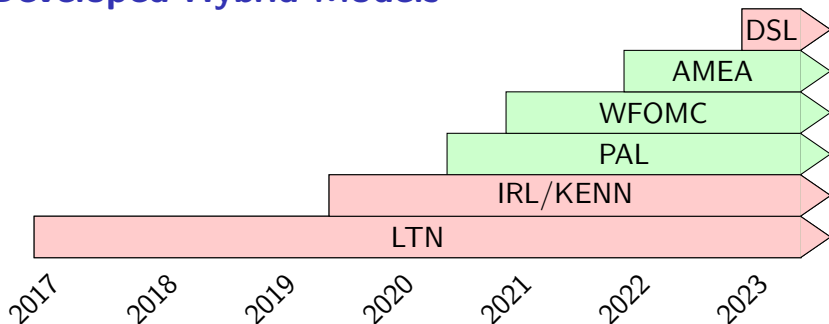
**PAL** Planning Acting and Learning

**WFOMC** Weighted First Order Model Counting

**AMEAI** Abstract Model for Embodied Agents

**DSL** Deep Symbolic Learning

# Developed Hybrid Models



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# Three integration modalities

There is not a unique way to integrate sub-symbolic and symbolic logical knowledge in a unique hybrid model. Three examples are the following:

- 1 subsymbolic models provides the **semantics** of logical symbols (LTN)
- 2 A symbolic system is used to **revise** the predictions done by a sub-symbolic system (IRL)
- 3 the model is the **composition** of two function a sub-symbolic function and a symbolic function (DSL)

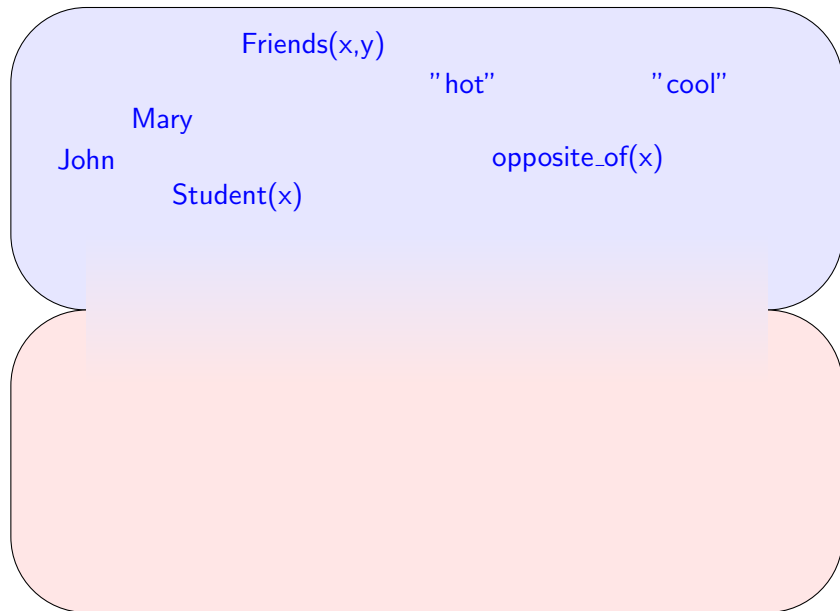


# LTN: Logic Tensor Network

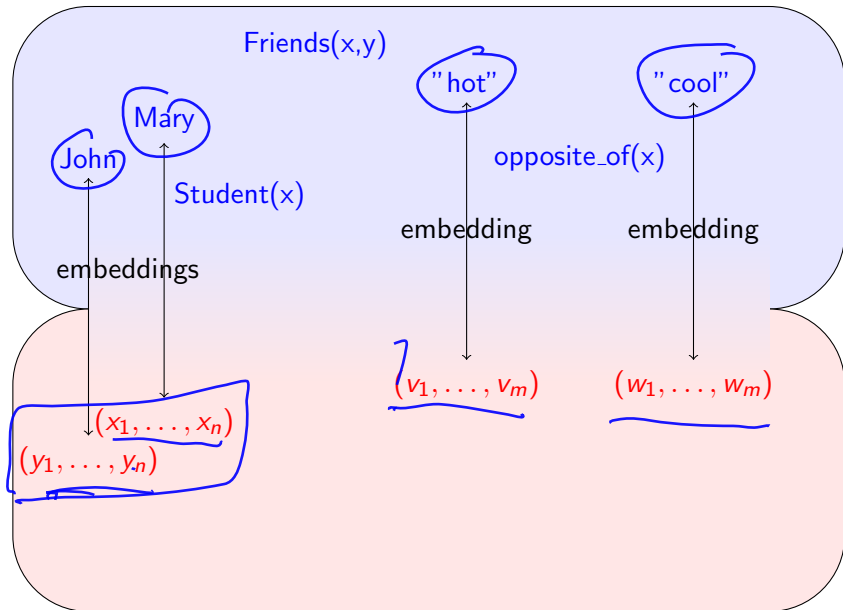
- inspired by the work by Gori and Diligenti on Semantic Regularization
- Logical symbols are grounded to real value functions (e.g., neural networks, embeddings, generative models)
- view logical formula as constraints that need to be satisfied by a base neural network
- Training data and constraints are encoded in logical formula
- Logical formulas  $\Rightarrow$  loss function
- Training  $\Rightarrow$  maximum satisfiability of logical formulas

Samy Badreddine et al. “Logic tensor networks”. In: *Artificial Intelligence* 303 (2022), p. 103649

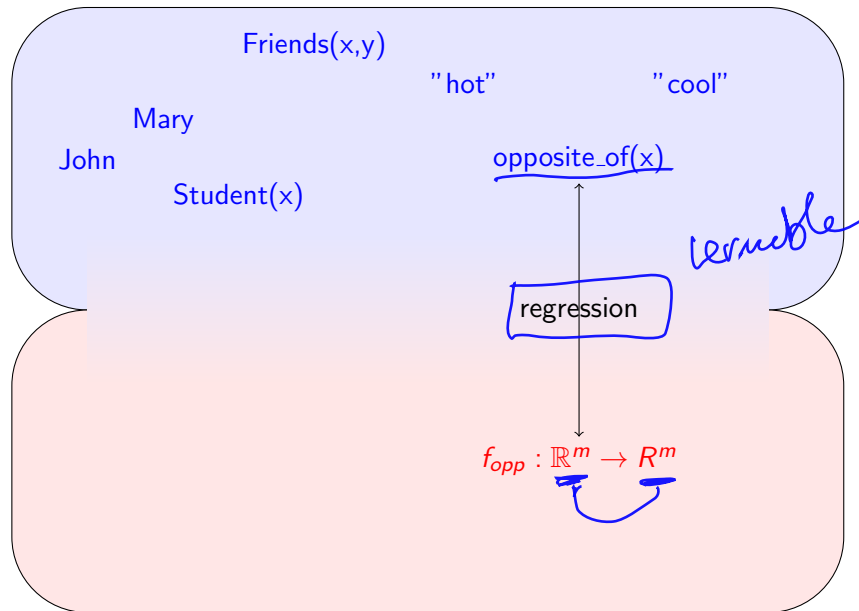
# Grounding FO Signature to sub-symbolic models



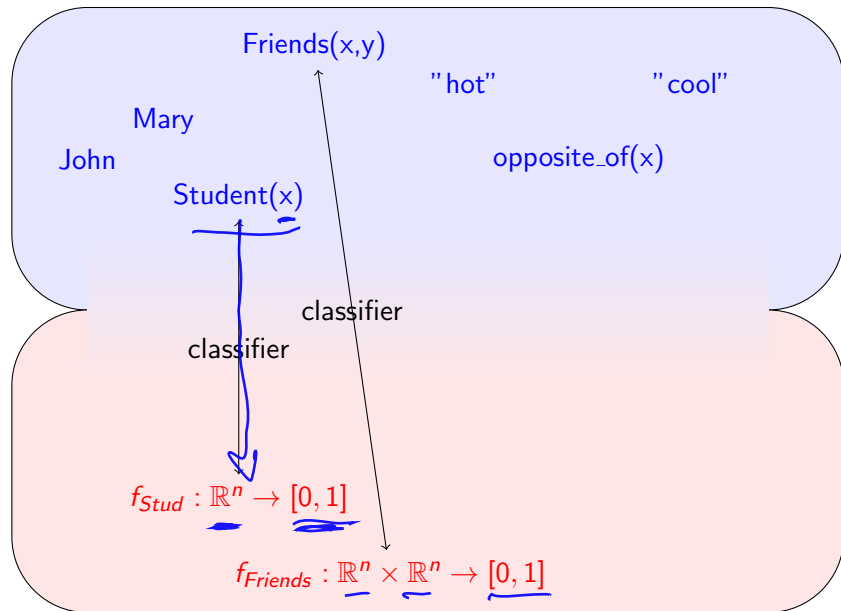
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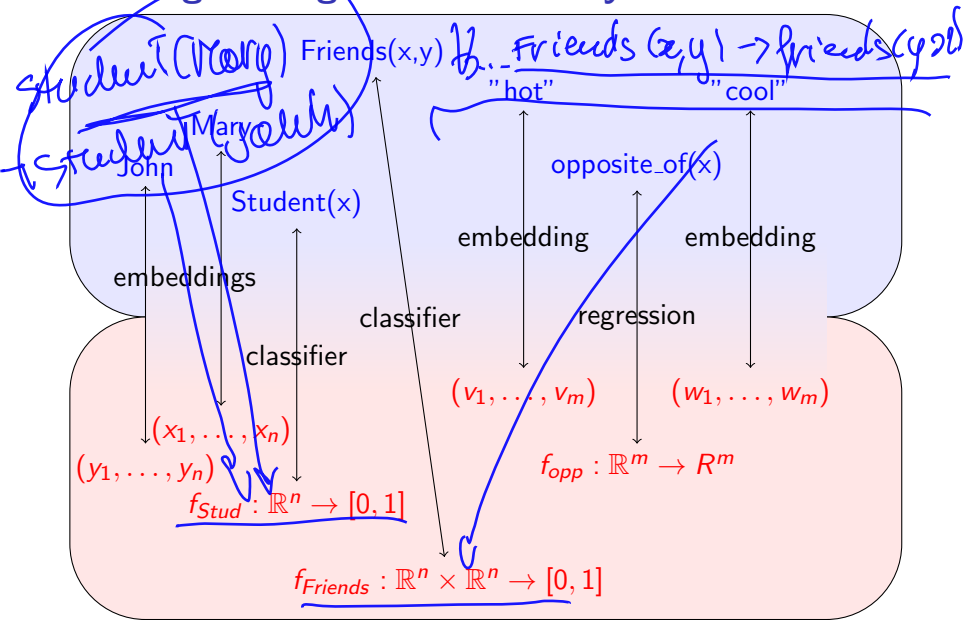
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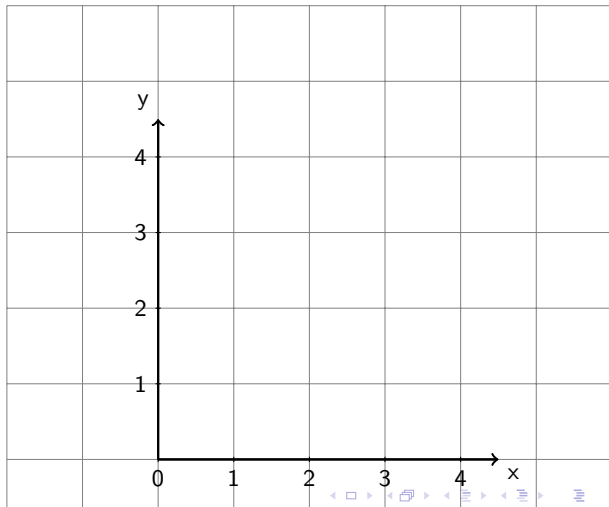


# Grounding FO Signature to sub-symbolic models



# Grounding FOL Signature in $\mathbb{R}^2$

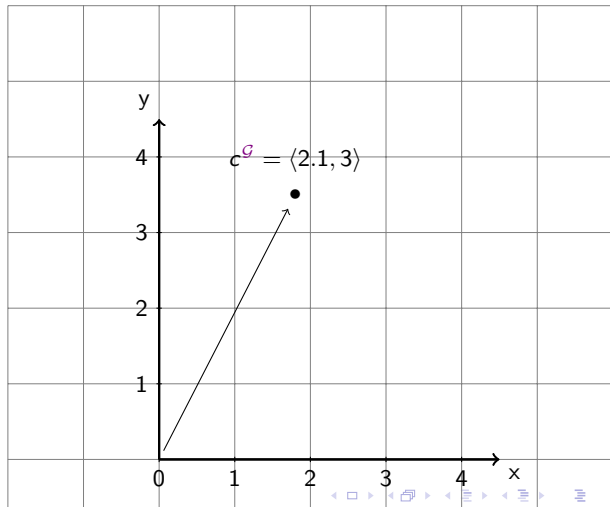
$$\Sigma = (c, d, f, P) \quad (1)$$



# Grounding FOL Signature in $\mathbb{R}^2$

$$\Sigma = (c, d, f, P) \quad (1)$$

- $c^{\mathcal{G}} = \langle 2.1, 3 \rangle$

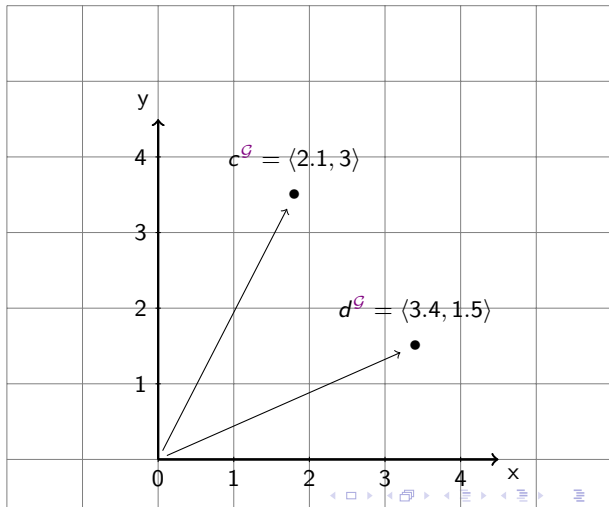




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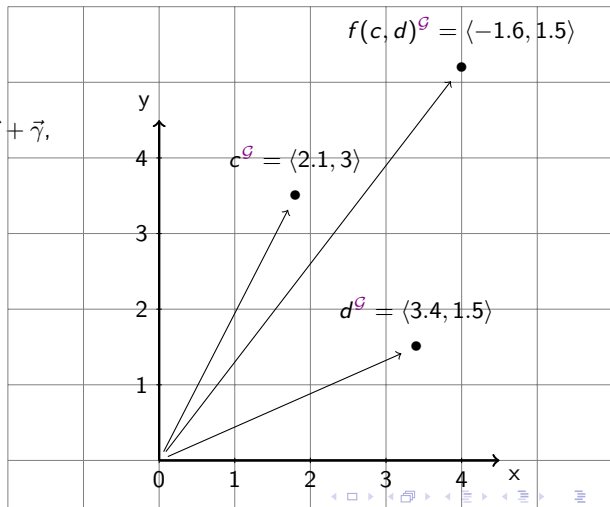
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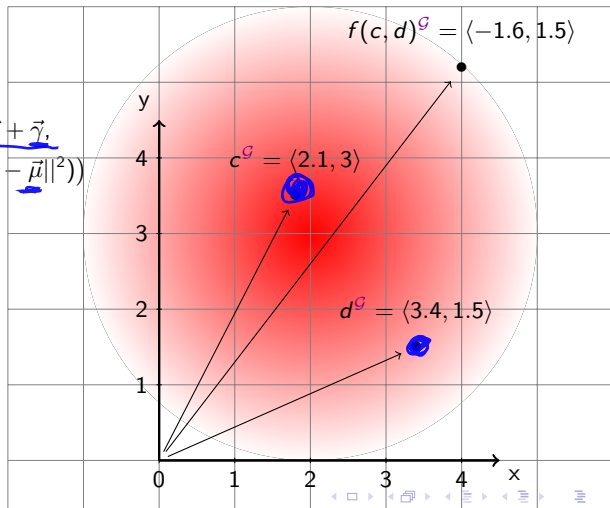
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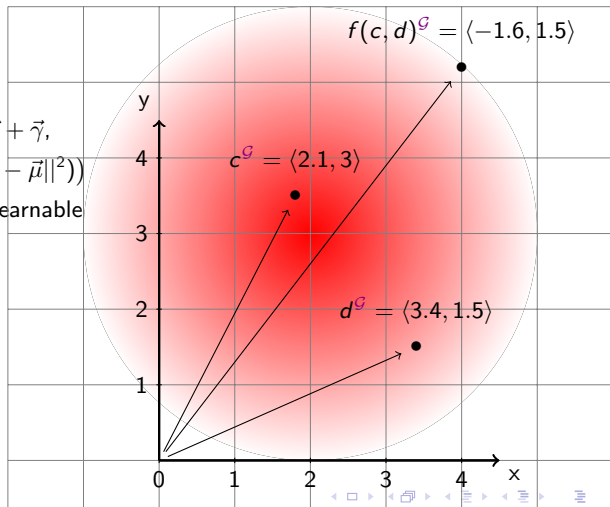


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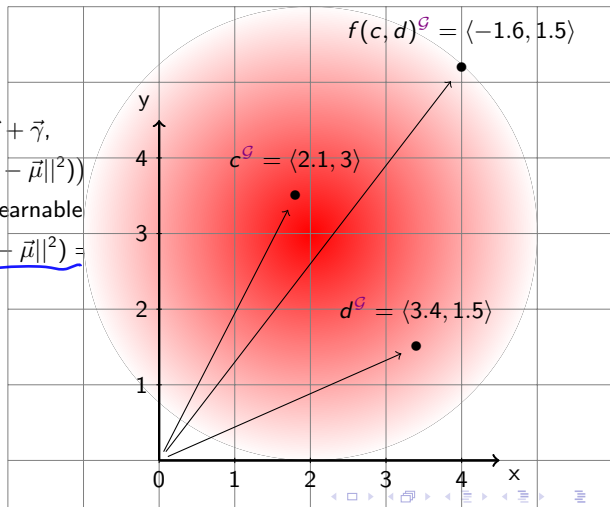
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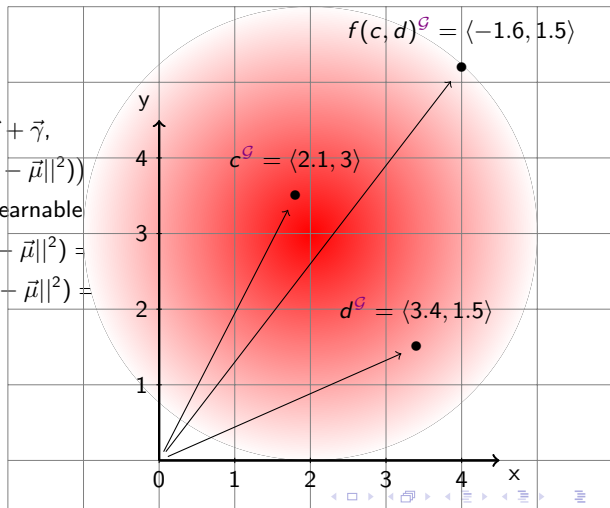
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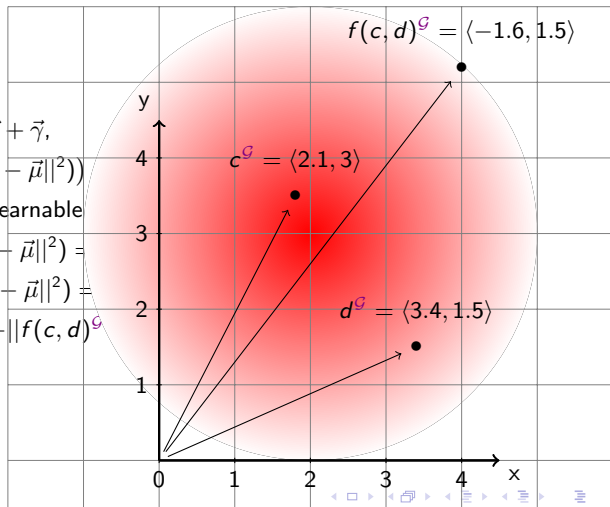
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- $P(f(c, d))^{\mathcal{G}} = \exp(-\|f(c, d)^{\mathcal{G}} - \vec{\mu}\|^2) = 1.95 * 10^{-6}$



# Grounding FOL propositional formulas

## Definition (Grounding of formulas)

The grounding of formulas is recursively defined according to their structure, and the **fuzzy semantics** of connectives.

- $P(t_1, \dots, t_n)^{\mathcal{G}} = P^{\mathcal{G}}(t_1^{\mathcal{G}}, \dots, t_n^{\mathcal{G}})$



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- $(\phi \vee \psi)^{\mathcal{G}} = \min(\phi^{\mathcal{G}} + \psi^{\mathcal{G}}, 1)$
- $(\neg \phi)^{\mathcal{G}} = 1 - \phi^{\mathcal{G}}$

## Alternative fuzzy operators

Examples:

$$(\phi \wedge \psi)^{\mathcal{G}} = \min(\phi^{\mathcal{G}}, \psi^{\mathcal{G}}) \quad (\text{Gödel T-norm})$$

$$(\phi \wedge \psi)^{\mathcal{G}} = \phi^{\mathcal{G}} \cdot \psi^{\mathcal{G}} \quad (\text{Product T-norm})$$

...

## Grounding FOL quantifiers

- The semantics of  $\forall x\phi(x)$  and  $\exists x\phi(x)$  is given in terms of aggregation functions  $Agg : [0, 1]^* \rightarrow [0, 1]$
- Every individual variable  $x$  is grounded in a  $m$ -tuple  $(x^{(1)}, \dots, x^{(m)})$  of elements in  $\mathbb{R}^n$
- $x^{\mathcal{G}}$  is obtained by sampling from  $\mathbb{R}^n$  according to some known data distribution.

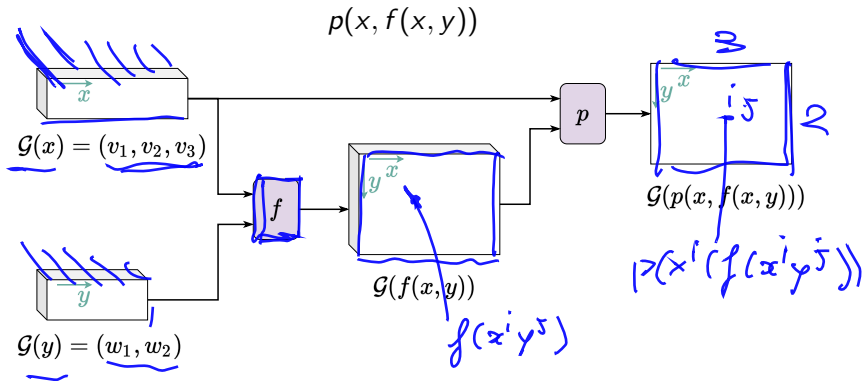
### Standard fuzzy semantics for quantifiers

$$(\forall x\phi(x))^{\mathcal{G}} = \min_{i=1}^m \phi(x^{(i)})^{\mathcal{G}} \quad (\exists x\phi(x))^{\mathcal{G}} = \max_{i=1}^m \phi(x^{(i)})^{\mathcal{G}}$$

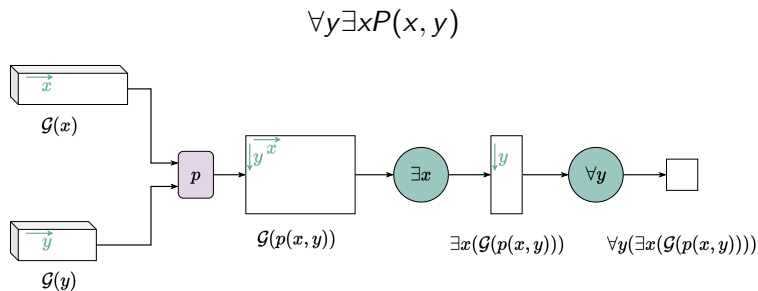
### Alternative parametrized semantics

$$(Qx\phi(x))^{\mathcal{G}} = \left( \frac{1}{m} \sum_{i=1}^m (\phi(x^{(i)})^{\mathcal{G}})^p \right)^{\frac{1}{p}}$$

# Computation graph of a formula $\phi$



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# Usage of LTN

- specify your learning problem in terms of  $\phi_1, \dots, \phi_n$
- Create the computational circuits for  $\phi_1, \dots, \phi_n$ ;
- train this circuit by minimizing the loss function

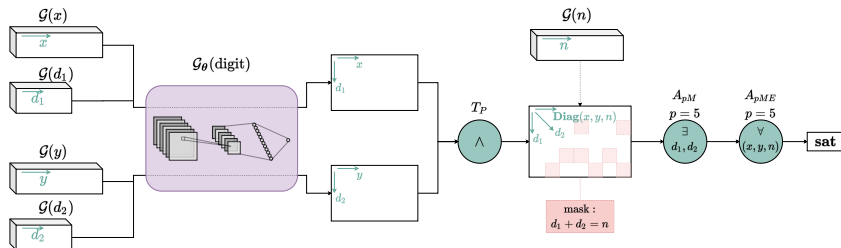
$$1 - \text{Agg}(\phi_1^{\mathcal{G}}, \dots, \phi_n^{\mathcal{G}})$$

where  $\text{Agg}$  is some aggregation operator for truth values.



# Mnist sum

$$\forall x, y, n (\exists d_1, d_2 ((d_1 + d_2 = n) \wedge \text{digit}(x, d_1) \wedge \text{digit}(y, d_2)))$$



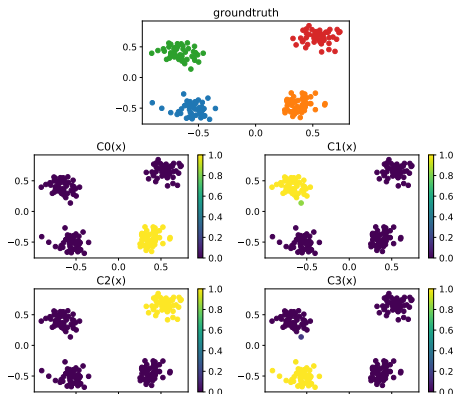
# Clustering

$$\forall x \exists c C(x, c)$$

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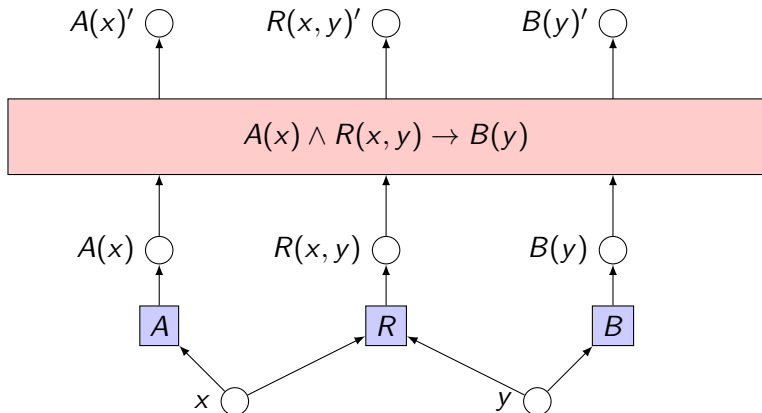
$$\forall x, y, c |x - y| < T_{close} : (C(x, c) \leftrightarrow C(y, c))$$

$$\forall x, y, c |x - y| > T_{dist} : \neg(C(x, c) \wedge C(y, c))$$



## IRL: Incremental Refinement layer

- In IRL the logical formulas (in clausal form) is like any other layer of a neural network. It takes in input the predictions of the predicates and return a modification of the prediction that better fits the formula



Alessandro Daniele et al. "Refining neural network predictions using background knowledge". In: *Machine Learning (2023)*, pp. 1–39

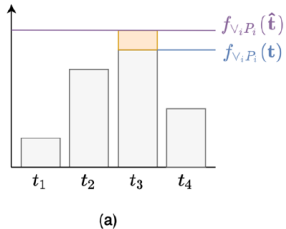
## Definition (Minimal Refinement function)

Let  $C = (l_1, \dots, l_n)$  be a clause. A minimal refinement function for a value  $w \in [0, 1]$  is a function  $f : [0, 1]^n \rightarrow [0, 1]^n$  such that

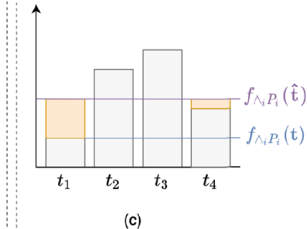
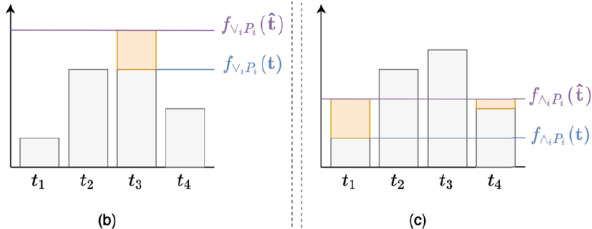
- $C(f(t_1, \dots, t_n)) = w$
- every other  $f' : [0, 1]^n \rightarrow [0, 1]^n$  such that  $C(f'(t_1, \dots, t_n)) = w$

$$\|f(\mathbf{t}) - \mathbf{t}\| \leq \|f'(\mathbf{t}) - \mathbf{t}\|$$

$$S_G(\mathbf{t}) = \max_i t_i$$



$$T_G(\mathbf{t}) = \min_i t_i$$

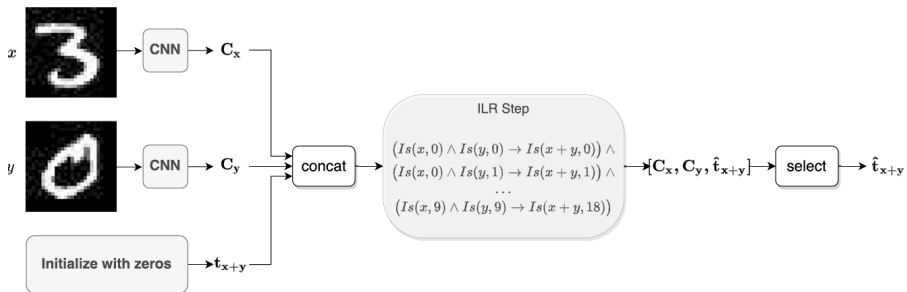


# Minimal Refinement function - General case

- refinement functions are defined for other operators ( $\wedge, \vee, \dots$ )
- Refinement functions can be defined for every formula as a composition of the refinement functions for each single operator.
- Analytic form for refinement function has been provided for an entire classes of fuzzy semantics that includes Product, Gödel, and Łukasiewicz.

Daniele et al., “Refining neural network predictions using background knowledge”

# Mnist Sum



# Deep Symbolic Learning

Learn end to end the composition of two functions

$$f \circ g$$

$$g(f_1(\mathbf{x}), f_2(\mathbf{y}))$$

- $f$  is the perception function

$$f : R^n \longrightarrow \{1, \dots, m\}$$

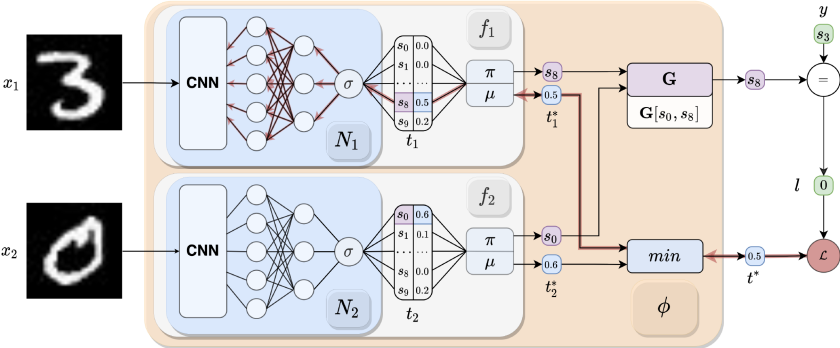
- $g$  is the discrete function

$$g : \{1, \dots, m\}^k \longrightarrow \{1, \dots, p\}$$

Alessandro Daniele et al. “Deep Symbolic Learning: Discovering Symbols and Rules from Perceptions”. In: *arXiv preprint arXiv:2208.11561* (2022).

To appear in IJCAI 2023

# Deep Symbolic Learning





# Conclusion

- There is not a unique way to combine logic and neural networks  
Frank Van Harmelen and Annette ten Teije. “A boxology of design patterns for hybrid learning and reasoning systems”. In: *arXiv preprint arXiv:1905.12389* (2019)
- I strongly believe that integrative approaches are better than encoding logic into non symbolic systems
- In this talk we have seen different approaches that have been used to solve the same class of problems (with similar results)
- As NeSy community we should develop benchmarks to evaluate and compare different approaches